Automated seismic interpretation using machine learning and field interpretations

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Espen Birger Raknes and Peder Aursand

Background

Goals

- Proof-of-concept study for predicting faults and horizons
- Real data needed to be involved
- Train using human interpretations from multiple fields
 - Exploration and production areas
- Binary sample prediction and pixel-level prediction (segmentation)
- **2D** and **3D** training data







APPROACH Training data work flow overview





APPROACH Neural network: Binary sample prediction



Note: Small version of the VGG architecture (Simonyan and Zisserman, 2014)



APPROACH Neural network: Pixel prediction (image segmentation)



Note: Small version of the SegNet architecture (Badrinarayanan et al., 2015)







RESULTS: FAULT PREDICTION Seismic slice



RESULTS: FAULT PREDICTION Heat map binary prediction





RESULTS: FAULT PREDICTION Heat map pixel prediction





RESULTS: HORIZON PREDICTION Seismic slice





RESULTS: HORIZON PREDICTION Heat map pixel prediction





RESULTS: HORIZON MULTI-FIELD TRAINING Seismic



RESULTS: HORIZON MULTI-FIELD TRAINING Heat map: Trained on one dataset

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RESULTS: HORIZON MULTI-FIELD TRAINING Heat map: Trained on another dataset





RESULTS: HORIZON MULTI-FIELD TRAINING Heat map: Trained on two datasets





Discussion and conclusion



Areas are different

- Differences in
 - Geology
 - Data quality
- Number of interpretations varies dependent on where the area is in the development phase

Suggestions

- More data to train on
- Representative data of the geology
- Model adaption to the area to be used on
- Apply techniques for preventing over-fitting





Using human interpretations

- Using human interpretations are not straight forward
- **Many** false negatives
- Very few false positives
- Non-symmetric label noise



Suggestions

- Use synthetic data
- Mix of synthetic and human-made data
- Manually QC-ed human-made data
- Use data from areas with enough interpretations





Straight lines are difficult

- Out-of-the box neural networks with standard loss functions struggle with finding straight lines
 - Learning best on objects with some «extent»
- Standard metrics not ideal

- New and better loss functions
- Take topology into account
- Post processing steps on the heat maps





Conclusion

Summary

- Image recognition by training models on human interpretations projected onto seismic samples
- Features predicted
 - Faults
 - Horizons

Challenges

- Non-symmetric label noise (false negatives) due to incomplete interpretations (manual data quality check is timeconsuming)
- Prediction accuracy suffers when applying a model to a different field
- Standard image recognition is not well suited for detecting lines and planes
- A reference data set for benchmarking these kinds of models is badly needed

Future work

- Transfer learning using pre-trained weights
- 3D data augmentation (transformations on real data or artificial data)
- Better metrics for FCNN
- Train on large combined datasets from multiple fields
- Pre-stack seismic data

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